

## 7.2 Equivalent Vector Channel

7.21. Recall that we are considering the digital modulator/demodulator part shown in Figure 37.

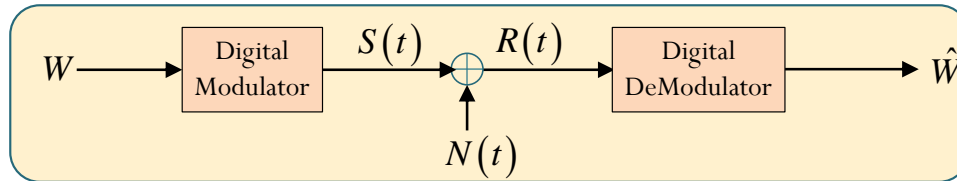


Figure 37: Digital modulator/demodulator and the waveform channel

7.22. The input of the modulator is the (random) message (index)  $W \in \{1, 2, \dots, M\}$ .

- Prior probabilities:  $p_j = P[W = j]$ .
- Each message is mapped to a waveform to be transmitted over the waveform channel as the transmitted waveform  $S(t)$ .
  - There are  $M$  possible messages. So, there are  $M$  waveforms:

$$s_1(t), s_2(t), \dots, s_M(t).$$

The (symbol) energy of the  $j$ -th waveform is  $E_j = \langle s_j(t), s_j(t) \rangle$ .

The average energy per symbol is  $E_s = \sum_{j=1}^M p_j E_j$ .

- Transmission of the message  $W = j$  is done by inputting the corresponding waveform  $s_j(t)$  into the channel. Therefore, the probability that the waveform  $s_j(t)$  is selected to be transmitted is the same as the probability that the  $j^{\text{th}}$  message occurs:

$$p_j = P[W = j] = P[S(t) = s_j(t)]$$

7.23. The noise  $N(t)$  in the channel is assumed to be additive. So, the receiver observes  $R(t) = S(t) + N(t)$ . The noise is also assumed to be independent from the transmitted waveform  $S(t)$ .

### 7.24. Conversion of Waveform Channels to Vector Channels:

(a) Given  $M$  waveforms  $s_1(t), s_2(t), \dots, s_M(t)$ , first find (possibly by GSOP) the  $K$  orthonormal basis functions  $\phi_1(t), \phi_2(t), \dots, \phi_K(t)$  for the space spanned by  $s_1(t), s_2(t), \dots, s_M(t)$ .

(b) The basis gives the vector representations  $\mathbf{s}^{(1)}, \mathbf{s}^{(2)}, \dots, \mathbf{s}^{(M)}$  for the waveforms  $s_1(t), s_2(t), \dots, s_M(t)$ , respectively. Note that  $s_i^{(j)}$ , the  $i^{\text{th}}$  component of the vector  $\mathbf{s}^{(j)}$ , comes from the inner-product:

$$s_i^{(j)} = \langle s_j(t), \phi_i(t) \rangle.$$

(c) The vector representations of the received waveform and the noise can then be calculated in a similar manner based on the derived basis.

(d) In summary, we convert the waveforms  $S(t), R(t)$ , and  $N(t)$  to their corresponding vectors  $\mathbf{S}, \mathbf{R}$ , and  $\mathbf{N}$  by performing inner-product with the orthonormal axes: the  $i$ -th component of the vector is the inner-product between the waveform and  $\phi_i(t)$ . In particular,

$$S_i = \langle S(t), \phi_i(t) \rangle, \quad R_i = \langle R(t), \phi_i(t) \rangle, \quad N_i = \langle N(t), \phi_i(t) \rangle.$$

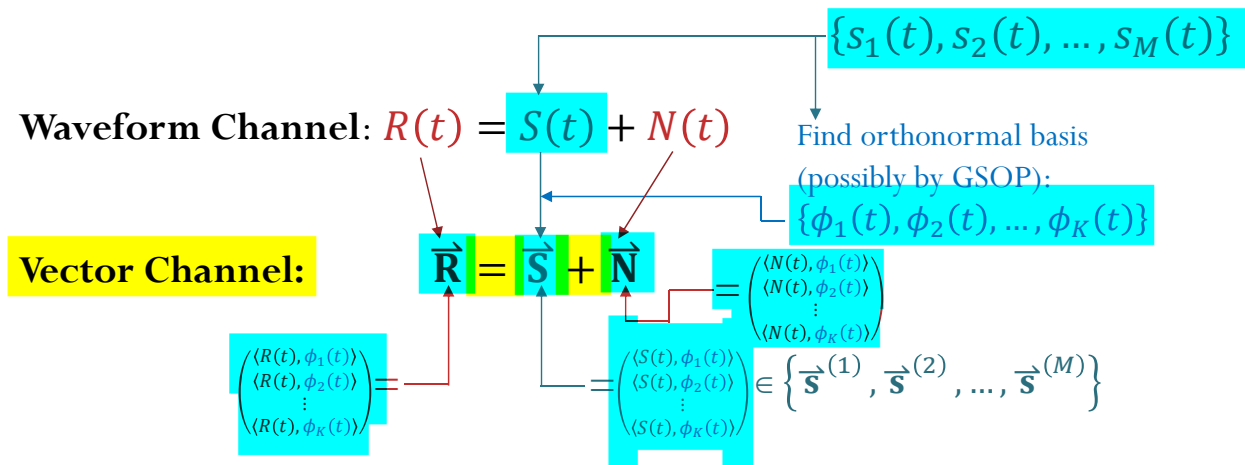


Figure 38: Conversion of Waveform Channels to Vector Channels

Remarks:

- We use the letter  $K$  instead of the letter  $N$  to represent the number of orthonormal basis functions to avoid the confusion with the random noise which is also denoted by the letter  $N$ .

- This conversion is the same as what we did when we convert waveforms to vectors via the GSOP. (See Eq. (38) and Figure 27a.) When  $s_j(t)$  is transmitted, the corresponding “transmitted” vector will be  $\mathbf{s}^{(j)}$ .

**Example 7.25.** Figure 39 illustrates how the message vectors in quaternary QAM are corrupted by additive noise.

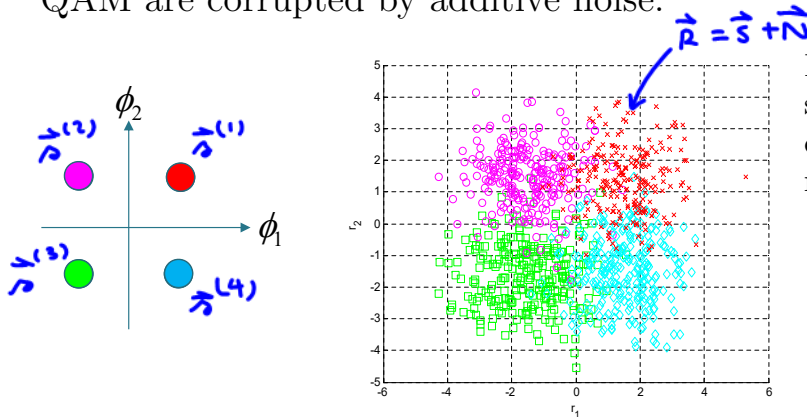


Figure 39: Quaternary QAM: constellation and samples of the received vectors (which are corrupted by additive noise)

**7.26.** Some facts that followed from the conversion:

- (a) For  $R(t) = S(t) + N(t)$ , we have  $\mathbf{R} = \mathbf{S} + \mathbf{N}$ .
- (b) From the perspective of designing optimal demodulator, the waveform channel and the vector channel are “equivalent”.

(c)  $E_j = \langle s_j(t), s_j(t) \rangle = \langle \mathbf{s}^{(j)}, \mathbf{s}^{(j)} \rangle$ .

$\langle r(t), s_j(t) \rangle = \langle \vec{r}, \vec{s}^{(j)} \rangle$

(d) Prior probabilities:

$$p_j = P[W = j] = P[S(t) = s_j(t)] = P[\mathbf{S} = \mathbf{s}^{(j)}]$$

(e)  $\mathbf{S} \perp \mathbf{N}$

(f) When  $N(t)$  is a white noise process with  $S_N(f) \equiv \frac{N_0}{2}$  (across all frequencies under consideration, we have

- (i)  $\mathbb{E}[N_j] = 0$ , and
- (ii)  $\mathbb{E}[N_i N_j] = \begin{cases} N_0/2, & i = j, \\ 0, & i \neq j. \end{cases}$

$N(t) \rightarrow \vec{N} = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_K \end{pmatrix}$

In other words, the noise components are uncorrelated and

$\text{Var } X = \mathbb{E}[X^2] - (\mathbb{E}X)^2$

$\mathbb{E}[N_i^2] = \text{Var } N_i = \frac{N_0}{2}$

$\sigma_{N_i} = \sqrt{\text{Var } N_i} = \sqrt{\frac{N_0}{2}}$